ADPRO

Contents

| ADPRO Driver | 3 |
|---|----|
| Driver specifications | 4 |
| Configuring the device's communication settings | 7 |
| Adding a communication driver to your project | 8 |
| Configuring the driver's communication settings | 9 |
| About driver worksheets | 10 |
| Adding and configuring a Standard Driver Sheet | 10 |
| Configuring the Main Driver Sheet | 17 |
| Additional notes | 20 |
| Checking the Driver Runtime task | 21 |
| Troubleshooting | 22 |
| Revision history | 27 |

ADPRO Driver

ADPRO Driver for Communication with AutomationDirect Productivity Series devices (version 1.10, last revised 14 June 2018).

The ADPRO driver enables communication between the Studio system and remote devices using the Modbus Extended protocol, according to the specifications discussed in this document.

This document assumes that you have read the "Development Environment" section in the main Studio documentation.

This document also assumes that you are familiar with the Microsoft Windows XP/Vista/7 environment. If you are not familiar with Windows, then we suggest using the **Help and Support** feature (available from the Windows **Start** menu) as you work through this document.

Driver specifications

This section identifies all of the software and hardware components required to implement communication between the ADPRO driver in Studio and remote devices using the Modbus Extended protocol.

Driver files

The ADPRO driver package comprises the following files, which are automatically installed in the Drv folder of the Studio application directory:

- ADPRO.DLL: Compiled driver.
- ADPRO.INI: Internal driver file. You must not modify this file.
- ADPRO.MSG: Internal driver file defining error messages for the possible error codes. (These error codes are described in detail in the Troubleshooting section.) You must not modify this file.
- ADPRO.PDF: This document, which provides complete information about using the driver.

Note: You must use a compatible PDF reader to view the ADPRO.PDF file. You can install Acrobat Reader from the Studio installation CD, or you can download it from Adobe's website.

You can use the ADPRO driver on the following operating systems:

- Windows Vista/7/8, Windows Server 2008
- Windows Embedded Compact 5.x/6.x

Device specifications

To establish communication, your target device must meet the following specifications:

- Manufacturer: AutomationDirect
- Compatible Equipment: Programmable Automation Controller (PAC) with firmware above 1.1.12.14
- Programmer Software:

The ADPRO driver supports the following device registers:

Supported registers

| System IDs | Description |
|------------|-------------------------|
| С | Internal Bit |
| SBR | System Read only Bit |
| SBRW | System Read/Write Bit |
| US8 | Unsigned 8 bits |
| S16 | Signed Integer 16 bits |
| BCD16 | BCD 16bits |
| US16 | Unsigned Integer 16bits |
| SWR | System Read only Word |
| SWRW | System Read/Write Word |
| S32 | Signed Integer 32bits |
| BCD32 | BCD 32bits |
| F32 | Float 32bits |

| STR | String |
|----------|----------------------------------|
| SSTR | System String |
| AR1C | Array 1D bit |
| AR1US8 | Array 1D Unsigned 8bits |
| AR1S16 | Array 1D Signed Integer 16bits |
| AR1US16 | Array 1D Unsigned Integer 16bits |
| AR1BCD16 | Array 1D BCD 16bits |
| AR1S32 | Array 1D Signed Integer 32bits |
| AR1BCD32 | Array 1D BCD 32bits |
| AR1F32 | Array 1D Float 32bits |
| AR1STR | Array 1D String |
| AR2C | Array 2D Bit |
| AR2US8 | Array 2D Unsigned 8bits |
| AR2S16 | Array 2D Signed Integer 16bits |
| AR2US16 | Array 2D Unsigned Integer 16bits |
| AR2BCD16 | Array 2D BCD16bits |
| AR2S32 | Array 2D Signed Integer 32bits |
| AR2BCD32 | Array 2D BCD 32bits |
| AR2F32 | Array 2D Float 32bits |
| AR2STR | Array 2D String |
| DI | Discrete In |
| DO | Discrete Out |
| MST | Module Status Bit |
| AIS32 | Analog In Signed 32bits |
| AOS32 | Analog Out Signed 32bits |
| AIF32 | Analog In Float 32bits |
| AOF32 | Analog Out Float 32bits |

Network specifications

To establish communication, your device network must meet the following specifications:

- Device Communication Port: 9999 or 502
- Physical Protocol: TCP/IP
- Logic Protocol: Modbus Extended
- Device Runtime Software: None
- Specific PC Board: None
- Cable Wiring Scheme: None

Conformance testing

The following hardware/software was used for conformance testing:

- Driver Version: 1.10
- Studio Version: 8.1 + P1
- Operating System (development): Windows 7/8
- Operating System (target): Windows 7/8
- Equipment: P3-550 CPU
- Communication Settings:
- TCP/IP Port: 9999/502
- Cable: Use specifications described in the "Network Specifications" section above.

Configuring the device's communication settings

This section explains how to configure the communication settings for the remote device.

All communication settings are handled automatically by the ADPRO protocol and development software. You do not need to configure anything on the target device.

Adding a communication driver to your project

This section explains how to add a communication driver to your project.

1. On the **Insert** tab of the ribbon, in the **Communication** group, click **Add/Remove Driver**. The *Communication Drivers* dialog is displayed.

| walabin | živer: | | |
|-----------|---|-------------|-------------|
| DLL. | Desciption | * | Hete |
| 43818 | Agiliert, High Parlomance Device (1.00) | 14 | |
| 9154 | 9154 - Controller 9154, Toledo Balance (+1.00) | | |
| A2420 | ALTUS, ALNET I Protocol with AL2420 [v1.04] | | |
| A290 | Driver for A250 Equipment (v1 26) | | |
| A500 | WEG - 4500 [V1 82] | | |
| AILIP | sides arades (russing rus suggrout re ((sure) | | (Alexandre |
| * M. | | | 1.3496.00 |
| elected o | tives: | | |
| OLL | Description | | Lit fishoo |
| | | | |
| | | | |
| | | | |
| | | | |
| | | | |
| | | | |
| | | | |
| | | 06 | Cantel |
| | | MTG - I - I | 10.00 10.00 |

Communication Drivers dialog

- 2. In the Available drivers list, click the communication driver that you want to add.
- 3. Click Select.

The driver is added to the Selected drivers list.

4. Click **OK**.

The *Communication Drivers* dialog is closed and the selected driver is inserted in the **Drivers** folder in the Project Explorer.

Configuring the driver's communication settings

This section explains how to configure the communication settings for the driver.

You must add the communication driver to your project before you can configure its settings. For more information, see Adding a communication driver to your project on page 8.

The general procedure for configuring a driver's communication settings is the same for all drivers. However, the specific settings are different for each driver, depending on the options and protocols used by the target device.

To configure the communication settings:

- In the **Comm** tab of the Project Explorer, expand the **Drivers** folder. The folder contains the drivers that are currently enabled. If you do not see the driver that you want to configure, then you need to add it.
- 2. Right-click the driver that you want to configure, and then click **Settings** on the shortcut menu. The *Communication Settings* dialog is displayed.

| - | | ADPR | .O: | | |
|-------------------------|----------|------|------------|------|--------|
| Serial Encapsulation | None | . ~ | | | |
| Serial Port COM: | COM2 | ÷ | Stop Bits: | 1 | v |
| Baud Rate: | 9600 | . ~ | Parity: | None | × |
| Data Bits: | 8 | Y | | | |
| MaxGap: | | St | ing 1: | | |
| 10 | | | | | |
| Long 2 | String 2 | | | | |
| 0 | | | | | |
| Advanced | 1 | | | OK | Cancel |

Communication Settings: ADPRO dialog

3. Configure the remaining, driver-specific settings as needed.

Driver-specific communication settings

| Setting | Default Value | Possible Values | Description |
|---------|---------------|-----------------|--|
| MaxGap | 10 | 1 to 999999 | It is set to specify the maximum difference between the addresses that is allowed to read in each block when reading in multiple blocks. |

4. Click **OK**.

The settings are saved and the Communication Settings dialog is closed.

About driver worksheets

Like the other parts of your project, communication with remote devices is controlled by worksheets. This section explains how to add worksheets to your project and then configure them to associate project tags with device registers.

Each selected driver includes a Main Driver Sheet (MDS) and one or more Standard Driver Sheets (SDS). The Main Driver Sheet is used to define tag/register associations and driver parameters that are in effect at all times, regardless of project behavior. In contrast, Standard Driver Sheets can be inserted to define tag/ register associations that are triggered by specific project behaviors.

The configuration of these worksheets is described in detail in the "Communication" chapter of the *Technical Reference Manual*, and the same general procedures are used for all drivers. Please review those procedures before continuing.

For the purposes of this document, only ADPRO driver-specific parameters and procedures are discussed here.

Adding and configuring a Standard Driver Sheet

By default, a communication driver does not include any Standard Driver Sheets. This section explains how to add a Standard Driver Sheet to your project and then configure it.

The ADPRO driver must be added to the project before you can configure any of its worksheets. For more information, see Adding a communication driver to your project on page 8.

Standard Driver Sheets can be inserted to define additional tag/register associations that are triggered by specific project behaviors.

Note: Most of the settings on this worksheet are standard for all drivers; for more information about configuring these settings, see the "Communication" chapter of the *Technical Reference Manual*. The Station and I/O Address fields, however, use syntax that is specific to the ADPRO driver.

1. Do one of the following.

- On the **Insert** tab of the ribbon, in the **Communication** group, click **Driver Sheet** and then select **ADPRO** from the list.
- In the **Comm** tab of the Project Explorer, right-click the **ADPRO** folder and click **Insert** on the shortcut menu. A new ADPRO driver worksheet is inserted into the **ADPRO** folder, and then it is automatically opened for configuring.

| Description | | | | | |
|---------------|----------------|----------------|---------------------|-------------|-----------------|
| | | | Inces | ie priority | |
| Read Trigger | Enable Read v | when I die: | Read Completed | i Rea | Statur: |
| Wele Trigger: | Enable Write o | n Tag Chan | ge: Write Completed | : Write | Status |
| Station | Header | | | | tr. [] |
| Tag Nar | ne | | vädress | Div | Add |
| C cuter best | Q Fit | G. Fitter text | | | iext Filter tex |

Standard Driver Sheet

Note: Worksheets are numbered in order of creation, so the first worksheet is ADPRO001.drv.

2. Configure the Station and Header fields as described below.

Station

Specify the IP address of the target device.

You can also specify an indirect tag (e.g. {MyStation}), but the tag that is referenced must follow the same syntax and contain a valid value.

Note: You cannot leave the **Station** field blank.

Header

Specify one of the following register types: С To access the Internal Bit SBR To access the System Read only Bit SBRW To access the System Read/Write Bit US8 To access the Unsigned 8 bits S16 To access the Signed Integer 16 bits BCD16 To access the BCD 16bits **US16** To access the Unsigned Integer 16bits SWR To access the System Read only Word SWRW To access the System Read/Write Word S32 To access the Signed Integer 32bits BCD32 To access the BCD 32bits F32 To access the Float 32bits STR To access the String SSTR To access the System String AR1C.ID To access the Array 1D bit AR1US8.ID To access the Array 1D Unsigned 8bits

AR1S16.ID To access the Array 1D Signed Integer 16bits AR1US16.ID To access the Array 1D Unsigned Integer 16bits AR1BCD16.ID To access the Array 1D BCD 16bits AR1S32.ID To access the Array 1D Signed Integer 32bits AR1BCD32.ID To access the Array 1D BCD 32bits AR1F32.ID To access the Array 1D Float 32bits AR1STR.ID To access Array 1D String AR2C.ID To access Array 2D Bit AR2US8.ID To access Array 2D Unsigned 8bits AR2S16.ID To access Array 2D Signed Integer 16bits AR2US16.ID To access Array 2D Unsigned Integer 16bits AR2BCD16.ID To access Array 2D BCD16bits AR2S32.ID To access Array 2D Signed Integer 32bits AR2BCD32.ID To access Array 2D BCD 32bits AR2F32.ID To access Array 2D Float 32bits AR2STR.ID To access Array 2D String DI To access Discrete In DO To access Discrete Out MST To access Module Status Bit AIS32 To access Analog In Signed 32bits AOS32 To access Analog Out Signed 32bits AIF32 To access Analog In Float 32bits AOF32 To access Analog Out Float 32bits ...where... **ID** The ID number of the array to be read.

After you edit the **Header** field, the development application checks the syntax to determine if it is valid. If the syntax is invalid, then the development application automatically inserts a default value of C.

You can also specify an indirect tag (e.g. {MyHeader}), but the tag that is referenced must follow the same syntax and contain a valid value.

3. For each tag/register association that you want to create, insert a row in the worksheet body and then configure the row's fields as described below.

Tag Name

Type the name of the project tag.

Address

Specify the address of the associated device register.

For C, SBR, SBRW, F32 system ID types, use the following syntax:

ID

...where... *ID*

The ID portion of the specific System ID to be read.

For US8, S16, BCD16, US16, SWR, SWRW, S32, BCD32system ID types, use the following syntax:

ID.Bit

...where... *ID*

The ID portion of the specific System ID to be read.

Bit

Read a specific bit of the System ID.

This is an optional parameter. If no bit is specified, then the entire register will be read.

For AR1C, AR1F32 array system ID types, use the following syntax:

Index

...where...Index

The index position of the specific element of the System ID array to be read.

For AR1US8, AR1S16, AR1US16, AR1BCD16, AR1S32, AR1BCD32 array system ID types, use the following syntax:

Index.Bit

...where...

IndexThe index position of the specific element of the System ID array to be read.BitRead a specific bit of the System ID array element.This is an optional parameter. If no bit is specified, then the entire register will be read.

For STR, SSTR string system ID types, use the following syntax:

ID. Length

...where...

ID The ID of the specific System ID string to be read.

Length

The length of the string to be read.

For AR1STR array, use the following syntax:

Index.Length

...where...

Index

The index position of the specific element of the System ID array to be read.

Length

The length of the string to be read.

For AR2C, AR2F32array system ID types, use the following syntax:

Index1.Index2

 \dots where \dots

Index1

The first dimension index of the specific element of the System ID array to be read.

Index2

The second dimension index of the specific element of the System ID array to be read.

For AR2US8, AR2S16, AR2US16, AR2BCD16, AR2S32, AR2BCD32array system ID types, use the following syntax:

Index1.Index2.Bit

...where...

Index1

The first dimension index of the specific element of the System ID array to be read.

Index2

The second dimension index of the specific element of the System ID array to be read.

Bit

Read a specific bit of the System ID array element.

This is an optional parameter. If no bit is specified, then the entire register will be read.

For AR2STRarray, use the following syntax:

Index1.Index2.Length

...where...

Index1

The first dimension index of the specific element of the System ID array to be read.

Index2

The second dimension index of the specific element of the System ID array to be read.

Length

The length of the string to be read.

For DI, DO, MST, AIS32, AOS32, AIF32, AOF32, use the following syntax:

Group.Base.Slot.Bit/Channel/Module

...where...

Group

The group number (00 = Local Group, 01 - 99 = Remote system).

Base

The base number.

Slot

The slot number.

Bit/Channel/Module

The DI/DO bit, AI/AO channel or module information number.

 Note: Each Standard Driver Sheet can have up to 4096 rows. However, the Read Trigger, Enable Read When Idle, and Write Trigger commands attempt to communicate the entire block of addresses that is configured in the sheet, so if the block of addresses is larger than the maximum block size that is supported by the driver protocol, then you will receive a communication error (e.g., "invalid block size") during run time. Therefore, the maximum block size imposes a practical limit on the number of rows in the sheet.

For examples of how device registers are specified using Header and Address, see the following table.

| System ID | Header | Address | |
|----------------------|------------|---------|--|
| US8-000250 | US8 | 250 | |
| AR1S16-000010[15] | AR1S16.10 | 15 | |
| AR2STR-000002(1)(12) | AR2STR.2 | 1.12.26 | |
| AR1BCD32-000003(5) | AR2BCD32.3 | 5.15 | |

Examples of Header and Address fields in Standard Driver Sheet

For more information about the device registers and addressing, please consult the manufacturer's documentation.

4. Save and close the worksheet.

Configuring the Main Driver Sheet

When you add the ADPRO driver to your project, the Main Driver Sheet is automatically included in the **ADPRO** folder in the Project Explorer. This section describes how to configure the worksheet.

The ADPRO driver must be added to the project before you can configure any of its worksheets. For more information, see Adding a communication driver to your project on page 8.

The Main Driver Sheet is used to define tag/register associations and driver parameters that are in effect at all times, regardless of project behavior. The worksheet is continuously processed during project runtime.

Note: Most of the settings on this worksheet are standard for all drivers; for more information about configuring these settings, see the "Communication" chapter of the *Technical Reference Manual*. The Station and I/O Address fields, however, use syntax that is specific to the ADPRO driver.

- 1. Do one of the following.
 - On the **Insert** tab of the ribbon, in the **Communication** group, click **Main Driver Sheet** and then select **ADPRO** from the list.
 - In the **Comm** tab of the Project Explorer, expand the **ADPRO** folder and then double-click **MAIN DRIVER SHEET**.

The Main Driver Sheet is displayed.

| Description MANUSAVERITIES Disable: | | | | | | | | | | | | |
|---|-------|----------------|---------------|-----|---------|---|-----|-------|---|----|-------------|------------|
| Read Completed | Read | Status | | | | | | | | | | |
| Write Completed | Write | Statue | | | | | | | | | | |
| Tag Name | - | Station | VO Address | | Action | _ | | Scan | _ | | Div | Add |
| Q. Filter text | | Q. Filter text | Q Filter text | Q, | (ILA) | | 2 | (All) | - | Q. | Filter text | Q Filter t |
| | | | | Rea | d+Write | - | Alw | ays | - | | | |
| | | | | Rea | d+Write | | Alw | ays | | | | |
| | | | | | | | | | | | | |

Main Driver Sheet

2. For each tag/register association that you want to create, insert a row in the worksheet body and then configure the row's fields as described below.

Tag Name

Type the name of the project tag.

Station

Specify the IP address and optionally the path (absolute or relative to the application's folder) to the exported tags database in CSV format of the target device, separated by a semi-colon. Example: 192.168.0.115;..\resources\P3000.csv

Note: You cannot leave the **Station**field blank.

I/O Address

C:ID To access the Internal Bit SBR:ID To access the System Read only Bit SBRW:ID To access the System Read/Write Bit US8:ID.Bit To access the Unsigned 8 bits S16:ID.Bit To access the Signed Integer 16 bits BCD16:ID.Bit To access the BCD 16bits US16:ID.Bit To access the Unsigned Integer 16bits SWR: ID. Bit To access the System Read only Word SWRW: ID.Bit To access the System Read/Write Word S32:ID.Bit To access the Signed Integer 32bits BCD32:ID.Bit To access the BCD 32bits F32:ID To access the Float 32bits STR: ID. Length To access the String SSTR: ID. Length To access the System String AR1C.ID:Index.Bit To access the Array 1D bit AR1US8.ID:Index.Bit To access the Array 1D Unsigned 8bits AR1S16.ID:Index.Bit To access the Array 1D Signed Integer 16bits AR1US16.ID:Index.Bit To access the Array 1D Unsigned Integer 16bits AR1BCD16.ID:Index.Bit To access the Array 1D BCD 16bits AR1S32.ID:Index.Bit To access the Array 1D Signed Integer 32bits AR1BCD32.ID:Index.Bit To access the Array 1D BCD 32bits AR1F32.ID:Index To access the Array 1D Float 32bits AR1STR.ID:Index.Length To access Array 1D String

AR2C.ID:Index1.Index2 To access Array 2D Bit AR2F32.ID:Index1.Index2 To access Array 2D Float 32bits AR2US8.ID:Index1.Index2.Bit To access Array 2D Unsigned 8bits AR2S16.ID:Index1.Index2.Bit To access Array 2D Signed Integer 16bits AR2US16.ID:Index1.Index2.Bit To access Array 2D Unsigned Integer 16bits AR2BCD16.ID:Index1.Index2.Bit To access Array 2D BCD16bits AR2S32.ID:Index1.Index2.Bit To access Array 2D Signed Integer 32bits AR2BCD32.ID:Index1.Index2.Bit To access Array 2D BCD 32bits AR2STR.ID:Index1.Index2.Length To access Array 2D String DI:Group.Base.Slot.Bit To access Discrete In DO:Group.Base.Slot.Bit To access Discrete Out MST:Group.Base.Slot.Module To access Module Status Bit AIS32:Group.Base.Slot.Channel To access Analog In Signed 32bits AOS32:Group.Base.Slot.Channel To access Analog Out Signed 32bits AIF32:Group.Base.Slot.Channel To access Analog In Float 32bits AOF32:Group.Base.Slot.Channel To access Analog Out Float 32bits

TAG: TagName

To access device addresses using tag names ...where...

ID

The ID portion of the specific System ID to be read.

Index

The index position of the specific element of the System ID array to be read.

Index1

The first dimension index of the specific element of the System ID array to be read.

Index2

The second dimension index of the specific element of the System ID array to be read.

Length

The length of the string to be read.

Bit

Read a specific bit of the System ID.

This is an optional parameter. If no bit is specified, then the entire register will be read.

Group

The group number (00 = Local Group, 01 – 99 = Remote system).

Base

The base number.

Slot

The slot number.

Bit

The DI/DO bit number.

Channel

The AI/AO channel number.

Module

The module information number.



3. Save and close the worksheet.

Additional notes

Additional notes about the ADPRO driver.

Block sizes

Block sizes depend on the register type. The protocol accepts messages of up to 240 bytes for read block commands and of up to 200 bytes or 25 blocks for read multiple blocks. For most of the headers this will give a fixed amount of registers, but for strings it is calculated on demand, based on the length of the strings. The following table shows the block size for each header.

| Header | Maximum Block Size |
|--|--|
| C, SBR, SBRW, AR1C | 1920 |
| US8, AR1US8 | 240 |
| S16, BCD16, US16, SWR, SWRW, AR1S16, AR1US16, AR1BCD16 | 120 |
| S32, BCD32, F32, AR1S32, AR1BCD32, AR1F32 | 60 |
| AR2C, AR2US8, AR2S16, AR2US16, AR2BCD16, AR2S32, AR2BCD32, AR2F32, DI, DO, MST, AIS32, AOS32, AIF32, AOF32 | 25 |
| STR, SSTR, AR1STR, AR2STR | Depends on string lengths configured on the PLC. |

Checking the Driver Runtime task

This section describes how to check the status of the Driver Runtime task in the list of execution tasks.

The Driver Runtime task handles communication with remote devices and the processing of the driver worksheets. By default, the task is configured to start up automatically when the project is run, but you can check it for yourself.

1. On the **Home** tab of the ribbon, in either the **Local Management** or the **Remote Management** group (depending on where you project server will be running), click **Tasks**. The *Project Status* dialog is displayed.

| Task | Sisture | 3Me | |
|--------------------------|---------|-----------|------|
| Background Task | | Automatic | 24 |
| M Core Runtime | | Atometic | |
| Distabane Spy | | Manual | 3 ar |
| Cotocow/ERP Purtone | | Manue | - |
| DOE Server | | Manual | - |
| B Drive Funtime | | Automatic | Seta |
| THDA OPC Server | | Manual | 1 |
| 5 LagVin | | Manuali | |
| BOORC Rymme | | Menual | |
| CIPC Net Client Purties | | Manual | |
| BORC IA Chart Buctime | | Manual | |
| CPC XML/DA Clert Ruttine | | Manual | |
| Studio Scata OPCServer | | Manual | |
| TCP/IP Client Rutline | | Manual | |
| CF/IF Server Runtme | | Menual | |
| Vervier | | Automotic | |

Project Status dialog

- 2. Verify that the **Driver Runtime** task is set to **Automatic**.
 - If the setting is correct, then proceed to the next step.
 - If the Driver Runtime task is set to Manual, select the task and then click Startup to change the task to Automatic.
- 3. Click **OK** to close the *Project Status* dialog.

Troubleshooting

This section lists the most common errors for this driver, their probable causes, and basic procedures to resolve them.

Checking status codes

If the ADPRO driver fails to communicate with the target device, then the database tag(s) that you configured for the **Read Status** and **Write Status** fields of the driver sheets will receive a status code. Use this status code and the following tables to identify what kind of failure occurred and how it might be resolved.

Status codes for the driver

| Status Code | Description | Possible Causes | Procedure To Solve |
|----------------|--|---|---|
| 0 | ОК | Communication without problems | None required |
| 1 | Error sending buffer | If using TCP/IP, the connection with the slave device might have been reset | Check the switches and network connection for failures |
| 2 | Invalid station on slave response | The response sent by the slave does not match the request made by the driver | Check for multiple masters on the network. Check the time out configuration settings (see section "Configuring the communication settings") and increase the time out. |
| 3 | Invalid CheckSum | Electrical interference on your connection | Check the physical connections on your network and verify if it is within the recommended physical layer specifications. |
| 4 | Invalid sequence number | The time out configured in the driver settings is too short | Check the time out configuration settings (see section "Configuring the communication settings") and increase the time out. |
| 7 | Invalid function code on slave response | The slave replied with a function code that does not match the request | Check for multiple masters on the network. Check the time out configuration settings (see section "Configuring the communication settings") and increase the time out. |
| 8 | Slave returned exception code | The slave could not comply with the driver request | Enable the protocol analyzer to see more details and the exception code returned, the message will help you to identify wrong settings (e.g.: unsupported address range) or list possible errors in the PLC |
| 9 | Invalid tag name | The driver could not find a tag name in the CSV file | Check if the tags being used in the application match the CSV file |
| 10 | Bit write not supported | The driver does not support writing to bits | Use Studio functionalities to change the bit and write the entire element |
| 11 | Invalid Max Gap. | MaxGap value shouldbe in the range from 1 to 999999 | Set MaxGap with value in the range 1 to 999999 |
| 101 | Illegal function code | Function code used by driver is not supported by device | Check with device manufacturer to support the function code |
| 102 | Illegal data address | Data address that is accessed by driver is non existent | Change the address in the driver sheet to address, which is present in the device |

| 103 | Illegal data value | Data value that is read from the address which is non existent | Change the address in the driver sheet to address, which is present in the device | |
|-----|---|---|---|--|
| 104 | Slave device failure | Unrecoverable error occurred in the device, performing the requested action | Device should be restarted, make sure that the requested action is valid. | |
| 105 | Acknowledge | Device taking more time to process request | Device will respond with appropriate response once processing is complete | |
| 106 | Slave device busy | Device is busy processing other request/ command | Request for read or write once the device is free | |
| 108 | Memory parity error | Parity error detected in device while reading the address | Device requires a service | |
| 110 | Gateway path unavailable | Gateway is misconfigured or overloaded | Check that gateway that is used for internal communication from input port to ouput port is properly configured | |
| 111 | Gateway target device failed to respond | Device is not present in the network | Check if the device is present | |

Common status codes

| Status Code | Description | Possible Causes | Procedure To Solve | |
|----------------|---|--|--|--|
| 0 | ОК | Communicating without error. | None required. | |
| -15 | Timeout waiting for message to start | Disconnected cables. PLC is turned off, in stop mode, or in error mode. Wrong station number. Wrong parity (for serial communication). Wrong RTS/CTS configuration (for serial communication). | Check cable wiring. Check the PLC mode — it must be RUN. Check the station number. Increase the timeout in the driver's advanced settings. Check the RTS/CTS configuration (for serial communication). | |
| -33 | Invalid driver configuration file | The driver configuration file (drivername.INI) is missing or corrupt. | Reinstall the driver. | |
| -34 | Invalid address | The specified address is invalid or out of range. | Check the supported range of addresses described in this document, and then correct the address. | |
| -35 | Driver API not initialized | The driver library was not initialized by the driver. | Contact technical support. | |
| -36 | Invalid data type | The specified data type is invalid or out of range. | Check the supported data types described in this document, and then correct the data type. | |
| -37 | Invalid header | The specified header in the driver worksheet is invalid or out of range. | Check the supported range of headers described in this document, and then correct the header. | |
| -38 | Invalid station | The specified station in the driver worksheet is invalid or out of range. | Check the supported station formats and parameters described in this document, and then correct the station. | |
| -39 | Invalid block size | Worksheet is configured with a range of addresses greater than the maximum block size. | Check the maximum block size number of registers described in this document, and then configure your driver worksheet to stay within that limit. Keep in mind that you can create additional worksheets. | |
| | | | Note: If you receive this error from a Main Driver Sheet or Tag Integration configuration, please contact Technical Support. | |
| -40 | Invalid bit write | Writing to a bit using the attempted action is not supported. | Writing to a bit using Write Trigger is not supported in some drivers. Modify the driver worksheet to use Write On Tag Change. The bit is read-only. | |
| -42 | Invalid bit number | The bit number specified in the address is invalid. The limit for the bit number depends on the registry type. | Check the addresses to see if there are bit numbers configured outside the valid range for the registry. | |
| -43 | Invalid byte number | The byte number specified in the address is invalid. The limit for the byte number depends on the registry type. | Check the addresses to see if there are byte numbers configured outside the valid range for the registry. | |

| Status Code | Description | Possible Causes | Procedure To Solve | |
|-------------|---|--|--|--|
| -44 | Invalid byte write | Writing to a byte using the attempted action is not supported. | The byte is read-only or inacessible. | |
| -45 | Invalid string size | The string is more than 1024 characters. | Modify the addresses that have string data type to be less than 1024 characters. | |
| -56 | Invalid connection handle | The connection is no longer valid. | Please contact Technical Support. | |
| -57 | Message could not be sent | The socket was unable to send the TCP or UDP message. | Check the station IP address and port number. | |
| | | | Confirm that the device is active and accessible. Try to ping the address. | |
| -58 | TCP/IP could not send all bytes | The TCP/IP stack was not able to send all bytes to destination. | Check the station IP address, port number and/or ID number. | |
| | | | Confirm that the device is active and accessible. | |
| | | | Try to ping the address. | |
| -60 | Error to establish TCP/IP connection | Error while establishing a TCP/IP connection with the slave device. Possibly incorrect IP address or port number in the specified | Check the station IP address, port number and/or ID number. | |
| | | | Confirm that the device is active and accessible. | |
| | | Station. | Try to ping the address. | |
| -61 | TCP/IP socket error | The TCP/IP connection has been closed by the device. | Confirm that the device is active and accessible. Try to ping the address. | |
| -62 | UDP/IP receive call returned error | The UDP socket is in error. | Check the station IP address, port number and/or ID number. | |
| | | | Confirm that the device is active and accessible. | |
| | | | Try to ping the address. | |
| -63 | UDP/IP error initializing | The UDP socket initialization failed. | Confirm that the operating system supports UDP sockets. | |
| -64 | UDP/IP receive call returned error | The UDP socket is in error. | Check the station IP address, port number and/or ID number. | |
| | | | Confirm that the device is active and accessible. | |
| | | | Try to ping the address. | |
| -65 | UDP/IP bind error, port number may already | The driver was not able to bind the UDP port. | Check the port number used by the driver. | |
| | be in use | | Check for other programs that might be bound to the UDP port. | |

Monitoring device communications

You can monitor communication status by establishing an event log in Studio's *Output* window (LogWin module). To establish a log for Field Read Commands, Field Write Commands and Serial Communication, right-click in the *Output* window and select the desired options from the pop-up menu.

You can also use the LogWin module to establish an event log on a remote unit that runs Windows Embedded. The log is saved on the unit in the celog.txt file, which can be downloaded later.

If you are unable to establish communication between Studio and the target device, then try instead to establish communication using the device's own programming software. Quite often, communication is interrupted by a hardware or cable problem or by a device configuration error. If you can successfully communicate using the programming software, then recheck the driver's communication settings in Studio.

Contacting Technical Support

If you must contact Technical Support, please have the following information ready:

- **Operating System** and **Project Information**: To find this information, click **Support** in the **Help** tab of the ribbon.
- **Driver Version** and **Communication Log**: Displays in the *Output* window (LogWin module) when the driver is enabled and the project is running is running.
- **Device Model** and **Boards**: Consult the hardware manufacturer's documentation for this information.

Revision history

This section provides a log of all changes made to the driver.

Revision history

| Driver Version | Revision Date | Description of Changes | Author |
|-------------------|-----------------|---|--------------------|
| 1.0 | 31 May 2013 | Initial release of driver. | André Körbes |
| 1.1 | 12 Sep 2013 | Updated status codes of read and write operations.Fixed lock on writing. | Charan Manjunath P |
| 1.2 | 27 Jan 2014 | Updated with MaxGap parameter in driver settings. Updated with status codes for invalid entry for MaxGap value. | Charan Manjunath P |
| 1.3 | 16 Oct 2014 | Fixed invalid block size error when reading analog datatypes. | Felipe Andrade |
| 1.4 | 20 Aug 2015 | Support for P Series family PLCs | Eduardo Castro |
| 1.5 | 10 Nov 2015 | •Fixed invalid block size error when reading string tags. | Anushree Phanse |
| 1.6 | 8 Jan 2016 | •Fixed invalid block size error when using screen tags. | Andre Korbes |
| 1.7 | 24 Apr 2017 | Fixed the issue of incorrectly reading C register values when MaxGap parameter is changed. | Anushree Phanse |
| 1.8 | 26 June 2017 | Improved performance when reading 1 dimensional arrays for all datatypes. (Note this improvement excludes strings or the header AR1STR) | Anushree Phanse |
| 1.9 | 27 October 2017 | Fixed issue of reading invalid values for C register for some MaxGap parameter values. | Anushree Phanse |
| 1.10 | 14 June 2018 | Fixed issue of driver crashing the application. | Anushree Phanse |